# DATASHEET - DC1-12015FB-A66OE1

**Variable frequency drive, 230 V AC, 1-phase, 15.3 A, 4 kW, IP66/NEMA 4X, Radio interference suppression filter, Brake chopper, 7-digital display assembly, Additional PCB protection, UV resistant, FS3**

Powering Business Worldwide™

**Part no.** DC1-12015FB-A66OE1
**Catalog No.** 199409

## Delivery program

| | | | |
|---|---|---|---|
| Photo | | |  |
| Product range | | | Variable frequency drives |
| Part group reference (e.g. DIL) | | | DC1 |
| Rated operational voltage | $U_e$ | | 230 V AC, 1-phase<br>240 V AC, single-phase |
| Output voltage with $V_e$ | $U_2$ | | 230 V AC, 3-phase<br>240 V AC, 3-phase |
| Mains voltage (50/60Hz) | $U_{LN}$ | V | 200 (-10%) - 240 (+10%) |
| **Rated operational current** | | | |
| At 150% overload | $I_e$ | A | 15.3 |
| Note | | | Rated operational current at an operating frequency of 6 kHz and an ambient air temperature of +40 °C |
| **Assigned motor rating** | | | |
| Note | | | For normal internally and externally ventilated four-pole three-phase asynchronous motors with 1500 rpm at 50 Hz and 1800 rpm at 60 Hz |
| Note | | | Overload cycle for 60 s every 600 s |
| Note | | | at 230 V, 50 Hz |
| 150 % Overload | P | kW | 4 |
| 150 % Overload | $I_M$ | A | 14.8 |
| Note | | | at 220 - 240 V, 60 Hz |
| 150 % Overload | P | HP | 5 |
| 150 % Overload | $I_M$ | A | 15.2 |
| Degree of Protection | | | IP66/NEMA 4X |
| Interface/field bus (built-in) | | | OP-Bus (RS485)/Modbus RTU, CANopen® |
| Fieldbus connection (optional) | | | SmartWire-DT |
| Fitted with | | | Radio interference suppression filter<br>Brake chopper<br>7-digital display assembly<br>Additional PCB protection<br>UV resistant |
| Parameterization | | | Keypad<br>Fieldbus<br>drivesConnect<br>drivesConnect mobile (App) |
| Frame size | | | FS3 |
| Connection to SmartWire-DT | | | no |

## Technical data

### General

| | | | |
|---|---|---|---|
| Standards | | | General requirements: IEC/EN 61800-2<br>EMV requirements: IEC/EN 61800-3<br>Safety requirements: IEC/EN 61800-5-1 |
| Certifications | | | CE, UL, cUL, RCM, Ukr SEPRO, EAC |

| | | | |
|---|---|---|---|
| Production quality | | | RoHS, ISO 9001 |
| Climatic proofing | $\rho_w$ | % | < 95%, average relative humidity (RH), non-condensing, non-corrosive |
| Air quality | | | 3C3, 3S3 |
| Ambient temperature | | | |
| Operating ambient temperature min. | | °C | -20 |
| Operating ambient temperature max. | | °C | + 40 |
| | | | operation (with 150 % overload) |
| Storage | ϑ | °C | -40 - +60 |
| Radio interference level | | | |
| Radio interference class (EMC) | | | C1 (for conducted emissions only), C2, C3, depending on the motor cable length, the connected load, and ambient conditions. External radio interference suppression filters (optional) may be necessary. |
| Environment (EMC) | | | 1st and 2nd environments as per EN 61800-3 |
| Mounting position | | | Vertical |
| Altitude | | m | 0–2000 m above sea level<br>Above 1000 m: 1% derating for every 100 m<br>max. 4000 m without UL |
| Degree of Protection | | | IP66/NEMA 4X |
| Protection against direct contact | | | BGV A3 (VBG4, finger- and back-of-hand proof) |

## Main circuit

| | | | |
|---|---|---|---|
| Supply | | | |
| Rated operational voltage | $U_e$ | | 230 V AC, 1-phase<br>240 V AC, single-phase |
| Mains voltage (50/60Hz) | $U_{LN}$ | V | 200 (-10%) - 240 (+10%) |
| Input current (150% overload) | $I_{LN}$ | A | 29.2 |
| System configuration | | | AC supply systems with earthed center point |
| Supply frequency | $f_{LN}$ | Hz | 50/60 |
| Frequency range | $f_{LN}$ | Hz | 48 - 62 |
| Mains switch-on frequency | | | Maximum of one time every 30 seconds |
| Power section | | | |
| Function | | | Variable frequency drive with internal DC link and IGBT inverter |
| Overload current (150% overload) | $I_L$ | A | 22.9 |
| max. starting current (High Overload) | $I_H$ | % | 175 |
| Note about max. starting current | | | for 2,5 seconds every 600 seconds |
| Output voltage with $V_e$ | $U_2$ | | 230 V AC, 3-phase<br>240 V AC, 3-phase |
| Output Frequency | $f_2$ | Hz | 0 - 50/60 (max. 500) |
| Switching frequency | $f_{PWM}$ | kHz | 8<br>adjustable 4 - 24 (audible) |
| Operation Mode | | | U/f control<br>Speed control with slip compensation<br>sensorless vector control (SLV)<br>PM motors<br>Synchronous reluctance motors<br>BLDC motors |
| Frequency resolution (setpoint value) | Δf | Hz | 0.1 |
| Rated operational current | | | |
| At 150% overload | $I_e$ | A | 15.3 |
| Note | | | Rated operational current at an operating frequency of 6 kHz and an ambient air temperature of +40 °C |
| Power loss | | | |
| Heat dissipation at rated operational current $I_e$ =150 % | $P_V$ | W | 120 |
| Efficiency | η | % | 97 |
| Heat dissipation at current/speed [%] | | | |
| Current = 100% | | | |
| Speed = 0 % | $P_V$ | W | 99.4 |
| Speed = 50 % | $P_V$ | W | 139.5 |
| Speed = 90 % | $P_V$ | W | 188.3 |
| Current = 50 % | | | |
| Speed = 0 % | $P_V$ | W | 65.6 |

| | | | |
|---|---|---|---|
| Speed = 50 % | $P_V$ | W | 83.3 |
| Speed = 90 % | $P_V$ | W | 107.6 |
| Current = 50 % | | | |
| Speed = 0 % | $P_V$ | W | 52.2 |
| Speed = 50 % | $P_V$ | W | 62.2 |
| Maximum leakage current to ground (PE) without motor | $I_{PE}$ | mA | 4.7 |
| Fitted with | | | Radio interference suppression filter<br>Brake chopper<br>7-digital display assembly<br>Additional PCB protection<br>UV resistant |
| Frame size | | | FS3 |
| Motor feeder | | | |
| Note | | | For normal internally and externally ventilated four-pole three-phase asynchronous motors with 1500 rpm at 50 Hz and 1800 rpm at 60 Hz |
| Note | | | Overload cycle for 60 s every 600 s |
| Note | | | at 230 V, 50 Hz |
| 150 % Overload | P | kW | 4 |
| Note | | | at 220 - 240 V, 60 Hz |
| 150 % Overload | P | HP | 5 |
| maximum permissible cable length | I | m | screened: 100<br>screened, with motor choke: 200<br>unscreened: 150<br>unscreened, with motor choke: 300 |
| Apparent power | | | |
| Apparent power at rated operation 230 V | S | kVA | 5.98 |
| Apparent power at rated operation 240 V | S | kVA | 6.24 |
| Braking function | | | |
| Standard braking torque | | | max. 30 % MN |
| DC braking torque | | | Max. 100% of rated operational current Ie, variable |
| Braking torque with external braking resistance | | | Max. 100% of rated operational current Ie with external braking resistor |
| minimum external braking resistance | $R_{min}$ | Ω | 25 |
| Switch-on threshold for the braking transistor | $U_{DC}$ | V | 390 V DC |

## Control section

| | | | |
|---|---|---|---|
| Reference voltage | $U_s$ | V | 10 V DC (max. 10 mA) |
| Analog inputs | | | 2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA |
| Analog outputs | | | 1, parameterizable, 0 - 10 V |
| Digital inputs | | | 4, parameterizable, max. 30 V DC |
| Digital outputs | | | 1, parameterizable, 24 V DC |
| Relay outputs | | | 1, parameterizable, N/O, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) |
| Interface/field bus (built-in) | | | OP-Bus (RS485)/Modbus RTU, CANopen® |

## Assigned switching and protective elements

| | | | |
|---|---|---|---|
| Power Wiring | | | |
| Safety device (fuse or miniature circuit-breaker) | | | |
| IEC (Type B, gG), 150 % | | | FAZ-B40/1N |
| UL (Class CC or J) | | A | 50 |
| Mains contactor | | | |
| 150 % overload (CT/$I_H$, at 50 °C) | | | DILM7<br>DILM7-…+DILM12-XP2 |
| Main choke | | | |
| 150 % overload (CT/$I_H$, at 50 °C) | | | DX-LN1-032 |
| Radio interference suppression filter (external, 150 %) | | | DX-EMC12-031-FS3 |
| Note regarding radio interference suppression filter | | | Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments |
| DC link connection | | | |
| Braking resistance | | | |
| 10 % duty factor (DF) | | | DX-BR035-1K1 |
| 20 % duty factor (DF) | | | DX-BR035-1K1 |
| 40 % duty factor (DF) | | | DX-BR040-3K1 |

| | | |
|---|---|---|
| Notes concerning braking resistances: | | The brake resistors are assigned based on the maximum rated power of the variable frequency drive. Additional brake resistors and designs (e.g. different duty cycles) are available upon request. |
| Motor feeder | | |
| motor choke | | |
| 150 % overload (CT/$I_H$, at 50 °C) | | DX-LM3-016 |
| Sine filter | | |
| 150 % overload (CT/$I_H$, at 50 °C) | | DX-SIN3-016 |
| All-pole sine filter | | |
| 150 % overload (CT/$I_H$, at 50 °C) | | DX-SIN3-024-A |

## Design verification as per IEC/EN 61439

| | | |
|---|---|---|
| Technical data for design verification | | |
| Operating ambient temperature min. | °C | -20 |
| Operating ambient temperature max. | °C | 40 |

## Technical data ETIM 7.0

Low-voltage industrial components (EG000017) / Frequency converter =< 1 kV (EC001857)

Electric engineering, automation, process control engineering / Electrical drive / Static frequency converter / Static frequency converter = < 1 kV (ecl@ss10.0.1-27-02-31-01 [AKE177014])

| | | |
|---|---|---|
| Mains voltage | V | 180 - 264 |
| Mains frequency | | 50/60 Hz |
| Number of phases input | | 1 |
| Number of phases output | | 3 |
| Max. output frequency | Hz | 500 |
| Max. output voltage | V | 250 |
| Nominal output current I2N | A | 11 |
| Max. output at quadratic load at rated output voltage | kW | 2.2 |
| Max. output at linear load at rated output voltage | kW | 2.2 |
| Relative symmetric net frequency tolerance | % | 10 |
| Relative symmetric net voltage tolerance | % | 10 |
| Number of analogue outputs | | 1 |
| Number of analogue inputs | | 2 |
| Number of digital outputs | | 1 |
| Number of digital inputs | | 4 |
| With control unit | | Yes |
| Application in industrial area permitted | | Yes |
| Application in domestic- and commercial area permitted | | Yes |
| Supporting protocol for TCP/IP | | No |
| Supporting protocol for PROFIBUS | | No |
| Supporting protocol for CAN | | Yes |
| Supporting protocol for INTERBUS | | No |
| Supporting protocol for ASI | | No |
| Supporting protocol for KNX | | No |
| Supporting protocol for MODBUS | | Yes |
| Supporting protocol for Data-Highway | | No |
| Supporting protocol for DeviceNet | | No |
| Supporting protocol for SUCONET | | No |
| Supporting protocol for LON | | No |
| Supporting protocol for PROFINET IO | | No |
| Supporting protocol for PROFINET CBA | | No |
| Supporting protocol for SERCOS | | No |
| Supporting protocol for Foundation Fieldbus | | No |
| Supporting protocol for EtherNet/IP | | Yes |
| Supporting protocol for AS-Interface Safety at Work | | No |
| Supporting protocol for DeviceNet Safety | | No |
| Supporting protocol for INTERBUS-Safety | | No |

| | | |
|---|---|---|
| Supporting protocol for PROFIsafe | | No |
| Supporting protocol for SafetyBUS p | | No |
| Supporting protocol for BACnet | | No |
| Supporting protocol for other bus systems | | Yes |
| Number of HW-interfaces industrial Ethernet | | 0 |
| Number of interfaces PROFINET | | 0 |
| Number of HW-interfaces RS-232 | | 0 |
| Number of HW-interfaces RS-422 | | 0 |
| Number of HW-interfaces RS-485 | | 1 |
| Number of HW-interfaces serial TTY | | 0 |
| Number of HW-interfaces USB | | 0 |
| Number of HW-interfaces parallel | | 0 |
| Number of HW-interfaces other | | 0 |
| With optical interface | | No |
| With PC connection | | Yes |
| Integrated breaking resistance | | Yes |
| 4-quadrant operation possible | | Yes |
| Type of converter | | U converter |
| Degree of protection (IP) | | IP66 |
| Degree of protection (NEMA) | | 4X |
| Height | mm | 310 |
| Width | mm | 210.5 |
| Depth | mm | 225.2 |

## Approvals

| | | |
|---|---|---|
| Product Standards | | UL 508C; CSA-C22.2 No. 14; IEC/EN61800-3; IEC/EN61800-5; CE marking |
| UL File No. | | E172143 |
| UL Category Control No. | | NMMS, NMMS7 |
| CSA File No. | | UL report applies to both US and Canada |
| North America Certification | | UL listed, certified by UL for use in Canada |
| Specially designed for North America | | No |
| Suitable for | | Branch circuits |
| Max. Voltage Rating | | 1~ 240 V AC IEC: TN-S UL/CSA: "Y" (Solidly Grounded Wey) |
| Degree of Protection | | IEC: IP66 |

## Dimensions